

E2-5 Signals & Linear Systems

Tutorial Sheet 3 - Solutions.

1. (a) $u(t) * u(t)$

$$\begin{aligned}
 &= \int_0^t u(\tau) u(t-\tau) d\tau \\
 &= \int_0^t d\tau = \tau \Big|_0^t = t \quad \text{for } t \geq 0 \\
 &= 0 \quad \text{for } t < 0
 \end{aligned}$$

$$\therefore u(t) * u(t) = t u(t)$$

(b) $e^{-at} u(t) * e^{-bt} u(t)$

$$\begin{aligned}
 &= \int_0^t e^{-a\tau} e^{-b(t-\tau)} d\tau = e^{-bt} \int_0^t e^{(b-a)\tau} d\tau \\
 &= \frac{e^{-bt}}{b-a} e^{(b-a)\tau} \Big|_0^t = \frac{e^{-bt}}{b-a} [e^{(b-a)t} - 1] \\
 &= \frac{e^{-at} - e^{-bt}}{a-b}
 \end{aligned}$$

Because both functions are causal, their convolution is zero for $t < 0$.

$$\therefore y(t) = e^{-at} u(t) * e^{-bt} u(t)$$

$$= \left(\frac{e^{-at} - e^{-bt}}{a-b} \right) u(t)$$

(c) Both functions are causal, \therefore

$$tu(t) * u(t) = \int_0^t \tau u(\tau) u(t-\tau) d\tau$$

For the range of integration, $0 \leq \tau \leq t$,

and $u(\tau)$ at $\tau=0$ is $u(0)=1$, at $\tau=t$ $u(t)=1$
and $u(t-\tau)$ at $\tau=0$ is $u(t)=1$, at $\tau=t$, $u(0)=1$

$$\therefore u(\tau) = u(t-\tau) = 1, \text{ and}$$

$$\begin{aligned} tu(t) * u(t) &= \int_0^t \tau d\tau \\ &= \frac{\tau^2}{2} \quad \text{for } t \geq 0 \\ &= 0 \quad \text{for } t < 0 \end{aligned}$$

$$\therefore \underline{y(t) = \frac{1}{2}t^2 u(t)}$$

2. a) $y(t) = \sin t u(t) * u(t)$

$$= \left[\int_0^t \sin \tau u(\tau) u(t-\tau) d\tau \right] u(t)$$

$$= \left[\int_0^t \sin \tau d\tau \right] u(t) \quad \begin{matrix} u(\tau) = 1 \\ u(t-\tau) = 1 \end{matrix}$$

$$= (1 - \cos t) u(t)$$

b) Similarly,

$$y(t) = \left[\int_0^t \cos \tau d\tau \right] u(t) = \sin t u(t)$$

$$3. \text{ a) } h(t) = e^{-t} u(t), \quad f(t) = u(t)$$

$$\begin{aligned} y(t) &= e^{-t} u(t) * u(t) \quad (\text{Pair #2}) \\ &= (1 - e^{-t}) u(t) \end{aligned}$$

$$\text{b) } f(t) = e^{-2t} u(t)$$

$$\begin{aligned} y(t) &= e^{-2t} u(t) * e^{-t} u(t) \quad (\text{Pair #4}) \\ &= (e^{-t} - e^{-2t}) u(t) \end{aligned}$$

$$\text{c) } f(t) = \sin 3t u(t)$$

$$y(t) = \sin 3t u(t) * e^{-t} u(t) \quad (\text{Pair #12})$$

$$\alpha = 0, \beta = 3, \theta = -90^\circ, \lambda = -1,$$

$$\therefore \phi = \tan^{-1} \left[\frac{-3}{-1} \right] = 108.4^\circ$$

$$\begin{aligned} \text{and } y(t) &= \frac{\cos(-90^\circ + 108.4^\circ) e^{-t} - \cos(3t + 18.4^\circ)}{\sqrt{(0-1)^2 + 3^2}} \\ &= \frac{0.9485 e^{-t} - \cos(3t + 18.4^\circ)}{\sqrt{10}} u(t) \end{aligned}$$

— · — · — Pair #12 — · — —

$$e^{-\alpha t} \cos(\beta t + \theta) u(t) * e^{\lambda t} u(t)$$

$$\Rightarrow \frac{\cos(\theta - \phi) e^{\lambda t} - e^{-\alpha t} \cos(\beta t + \theta - \phi)}{\sqrt{(\alpha + \lambda)^2 + \beta^2}} u(t)$$

$$\phi = \tan^{-1} \left[-\beta / (\alpha + \lambda) \right]$$

4. The key is to realise that

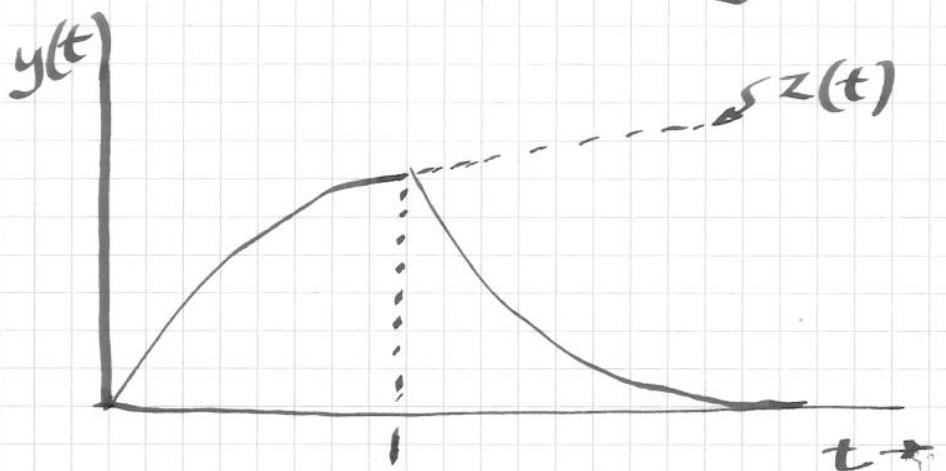
$$f(t) = u(t) - u(t-1)$$

$$\therefore e^{-t} u(t) * u(t) \Leftrightarrow \underbrace{(1 - e^{-t}) u(t)}_{z(t)} \quad \textcircled{A}$$

$$\begin{aligned} e^{-t} u(t) * u(t-1) &\Rightarrow z(t-1) \\ &= [1 - e^{-(t-1)}] u(t-1) \end{aligned} \quad \textcircled{B}$$

$$\begin{aligned} \therefore y(t) &= e^{-t} u(t) * [u(t) - u(t-1)] \\ &= (\text{A} - \text{B}) \quad \text{superposition} \end{aligned}$$

$$= (1 - e^{-t}) u(t) - [1 - e^{-(t-1)}] u(t-1)$$



$$Q5a) \cdot h(t) = -\delta(t) + 2e^{-t}u(t)$$

$$x(t) = e^t u(-t)$$

$$y(t) = h(t) * x(t)$$

$$= [-\delta(t) + 2e^{-t}u(t)] * e^t u(-t)$$

$$= -\delta(t) * e^t u(-t) + 2e^{-t}u(t) * e^t u(-t)$$

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$$-e^t u(-t)$$

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See convolution
table no: 13,
lecture 5-5

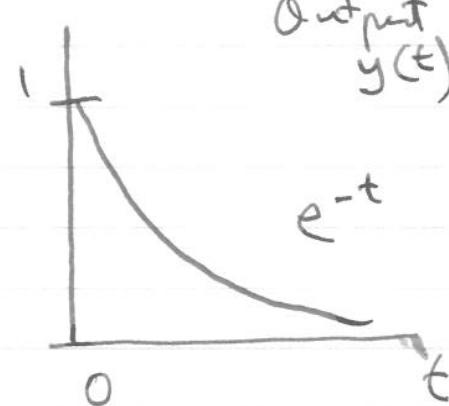
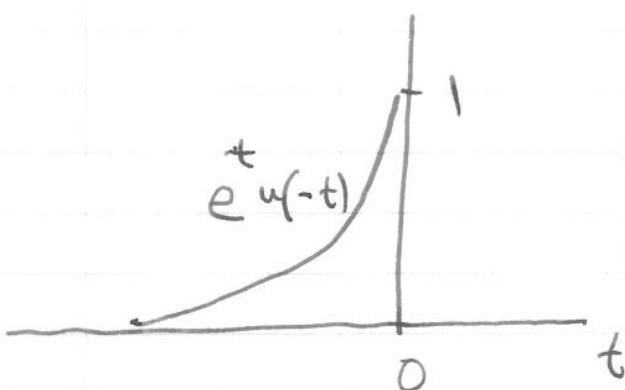
$$2 \left[\frac{e^{-t}u(t) + e^t u(-t)}{2} \right]$$

$$\therefore y(t) = \cancel{-e^t u(-t)} + e^{-t}u(t) + \cancel{e^t u(-t)}$$

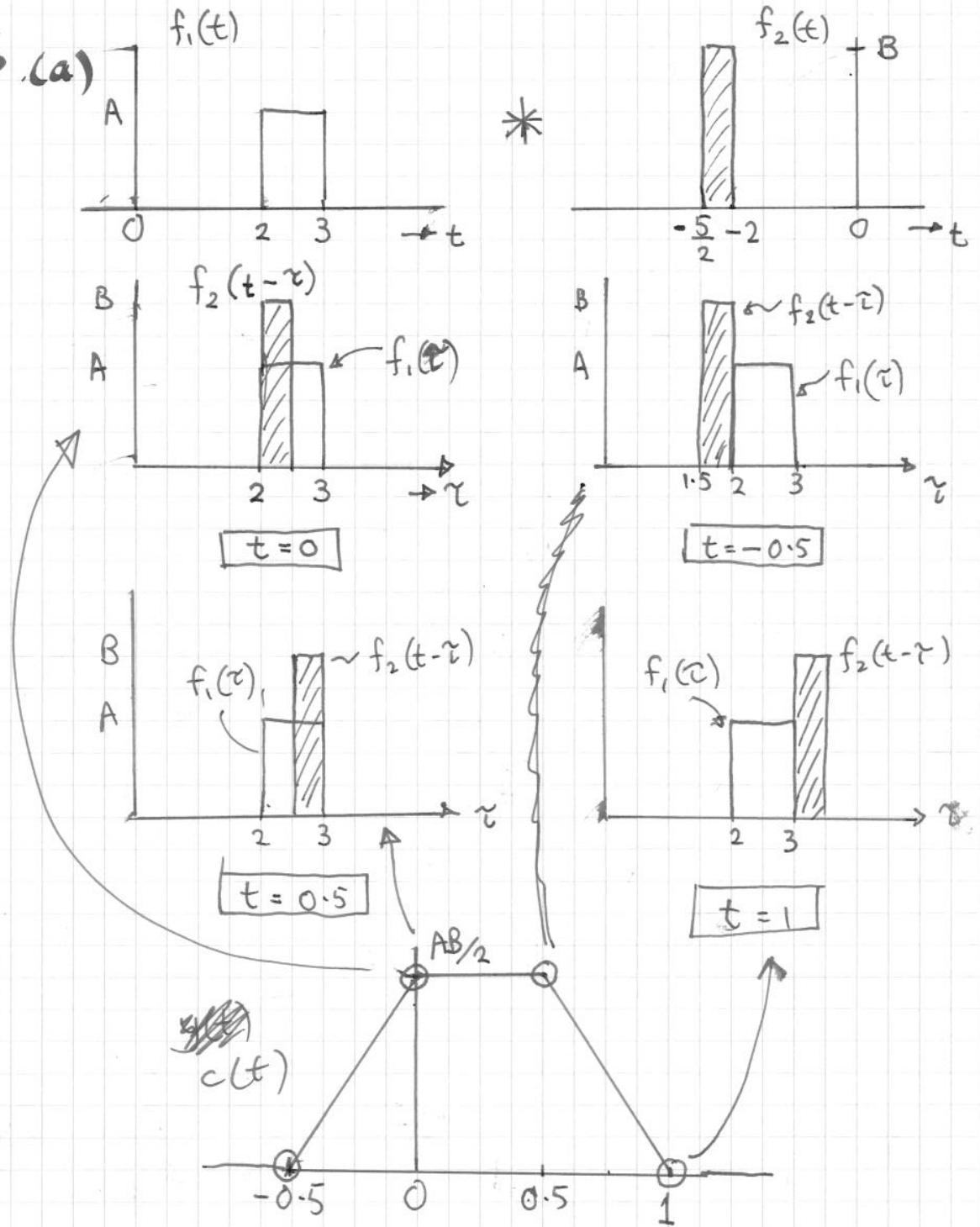
$$= e^{-t}u(t)$$

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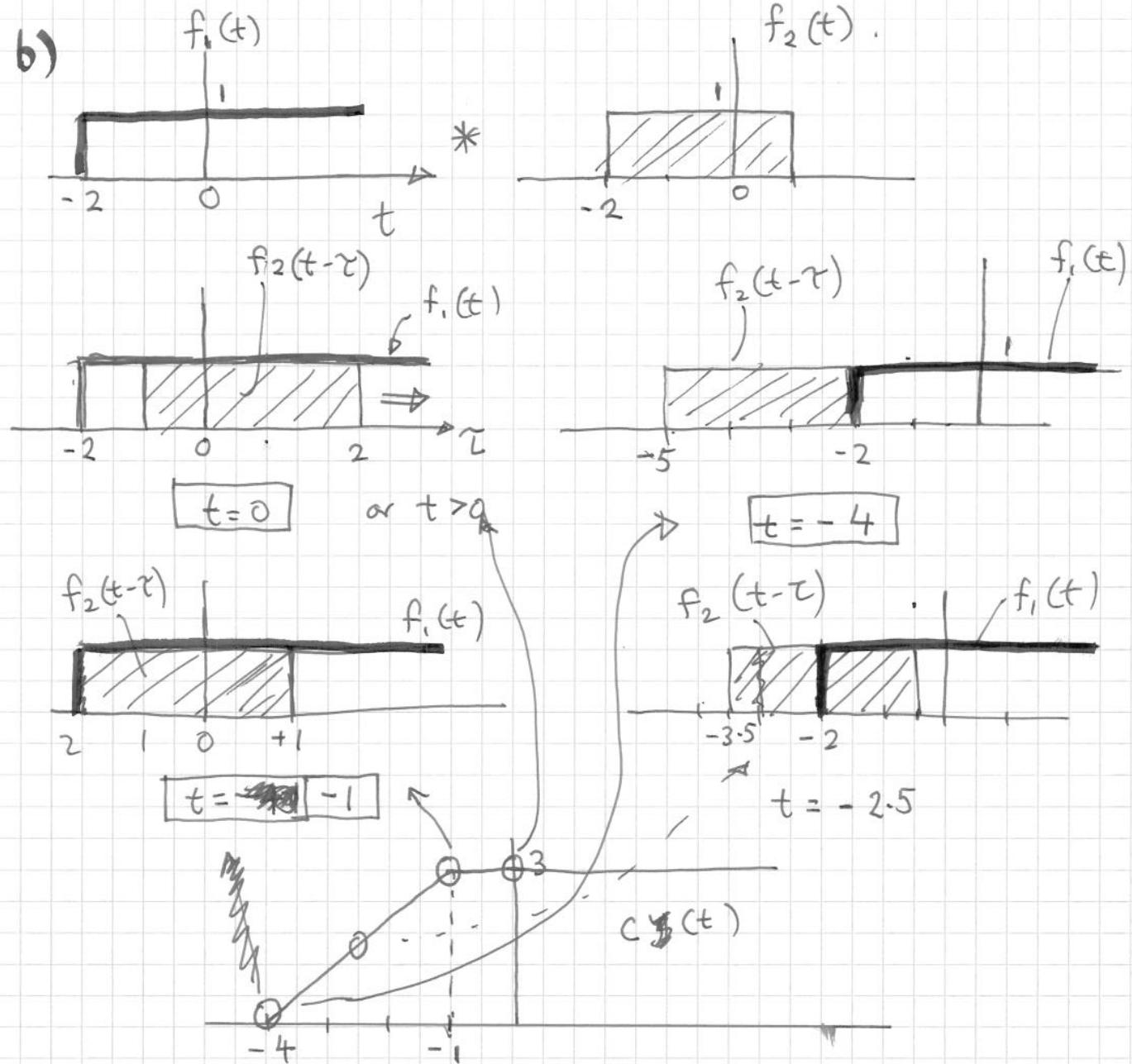
b) input $x(t)$



Q6 (a)



6. b)

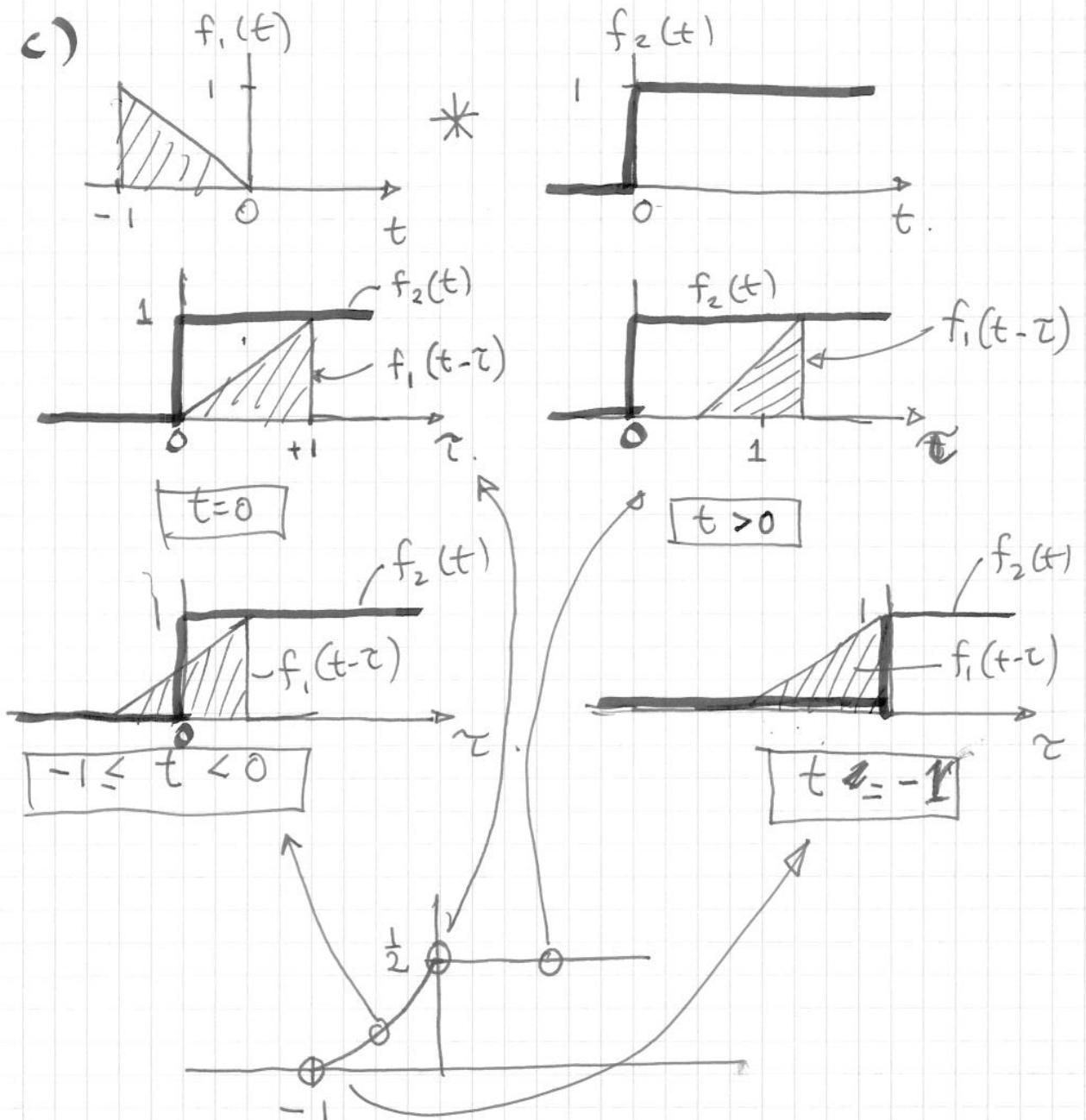


$$c(t) = \int_{-1+t}^{2+t} dt = 3 \quad t \geq -1$$

$$c(t) = \int_{-2}^{2+t} d\tau = t + 4 \quad -1 \geq t \geq -4$$

$$c(t) = 0 \quad t \leq -4$$

6 c)



Note : Easy to do $\int f_2(\tau) f_1(t-\tau) d\tau$

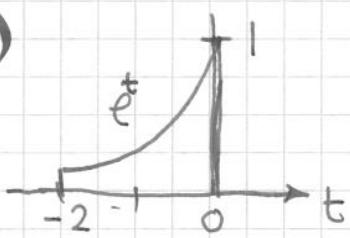
$$c(t) = \int_t^{t+1} (\tau - t) d\tau = \frac{1}{2} t^2 \quad t \geq 0$$

$$c(t) = \int_0^{t+1} (\tau - t) d\tau = \frac{1}{2} (1-t^2) \quad 0 \geq t \geq -1$$

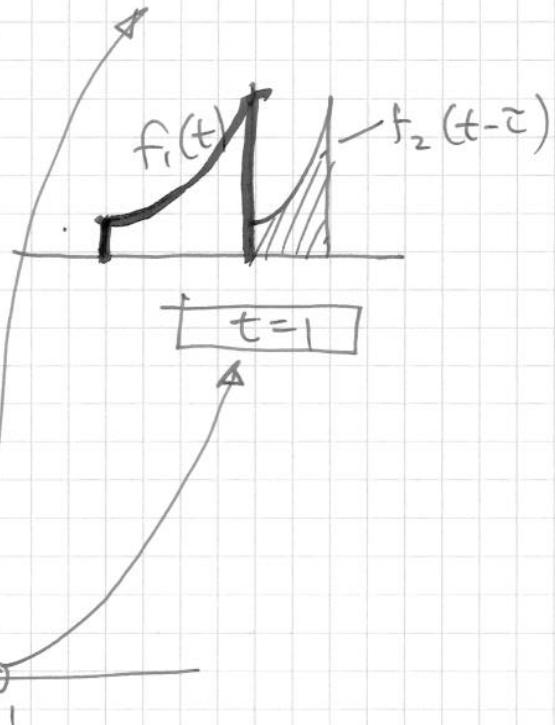
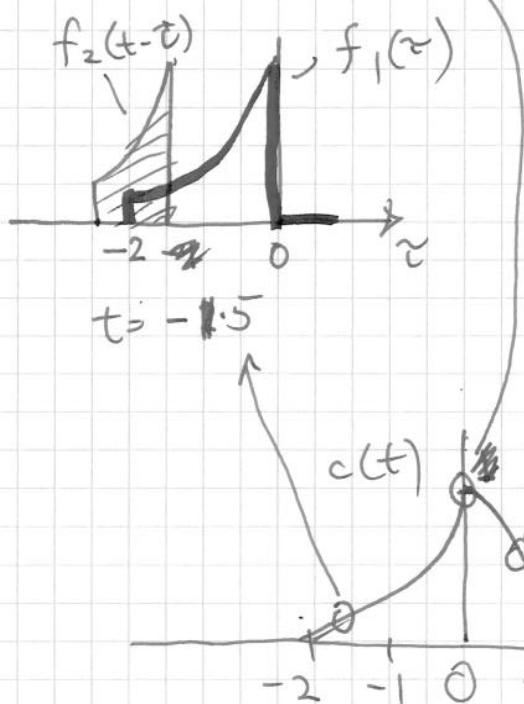
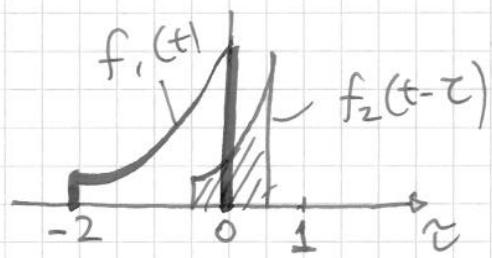
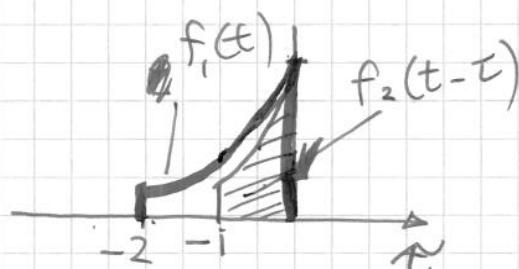
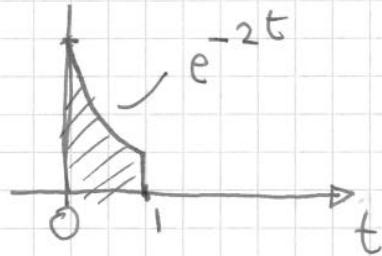
$$c(t) = 0 \quad t < -1$$

6 d)

$$f_1(t)$$

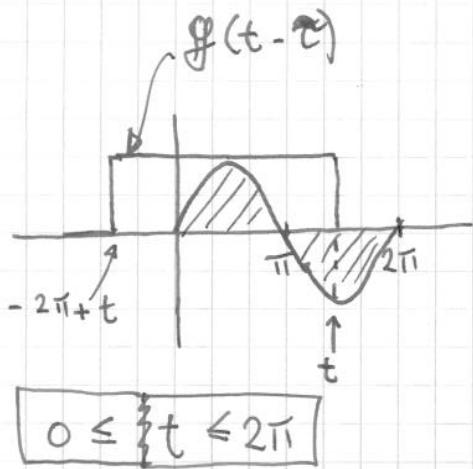


$$f_2(t)$$

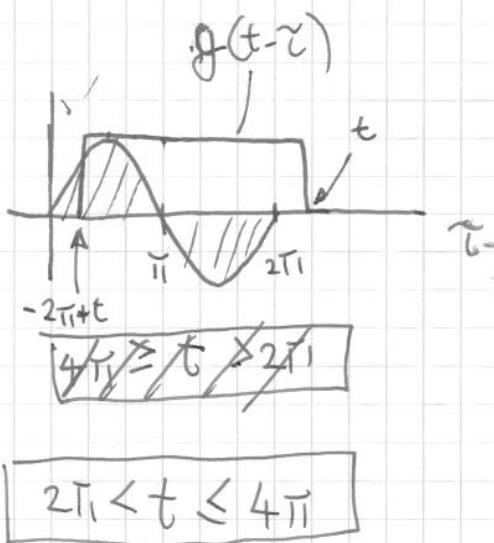


S3.9

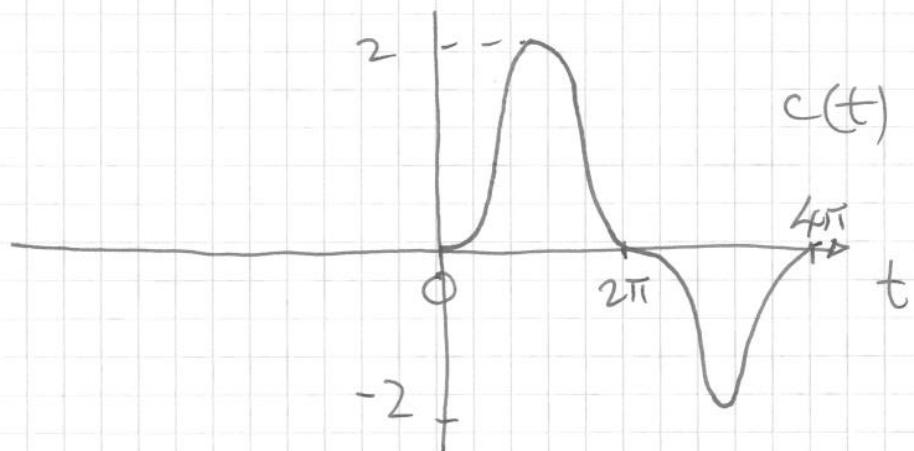
7)



$$\begin{aligned} f(t) * g(t) &= \int_0^t \sin r dr \quad 0 \leq t \leq 2\pi \\ &= 1 - \cos t \end{aligned}$$

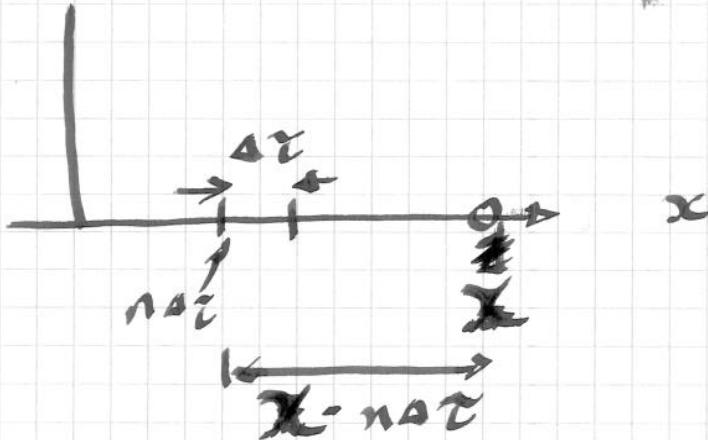


$$\begin{aligned} f(t) * g(t) &= \int_{t-2\pi}^{2\pi} \sin r dr \\ &= \cos t - 1 \quad 2\pi < t \leq 4\pi \end{aligned}$$



53 · 10
53 · 9

8.



An element of length Δz at point $n\Delta z$ has a charge $f(n\Delta z) \Delta z$.

The electric field due to this charge at point x is

$$\Delta E = \frac{f(n\Delta z) \Delta z \times q}{4\pi \epsilon (x - n\Delta z)^2}$$

∴ Total Field E due to charge along the entire length is

$$E(x) = \lim_{\Delta z \rightarrow 0} \sum_{n=-\infty}^{\infty} \frac{f(n\Delta z) \Delta z \times q}{4\pi \epsilon (x - n\Delta z)^2}$$

$$= \int_{-\infty}^{\infty} \frac{f(z) q}{4\pi \epsilon (x - z)^2} dz$$

$$= f(x) * \frac{q}{4\pi \epsilon x^2}$$

$$= f(x) * h(x)$$

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